

Leveraging Multiple Continuous Monitoring Sensors for Emissions Alerting on Oil and Gas Facilities

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The problem

Given a number of continuous monitoring sensors on an oil and gas facility, can we deliver concise alerts when an actionable event occurs?



Colorado State University's
METEC Facility

Oil and gas test facility capable
of controlled emissions

The problem

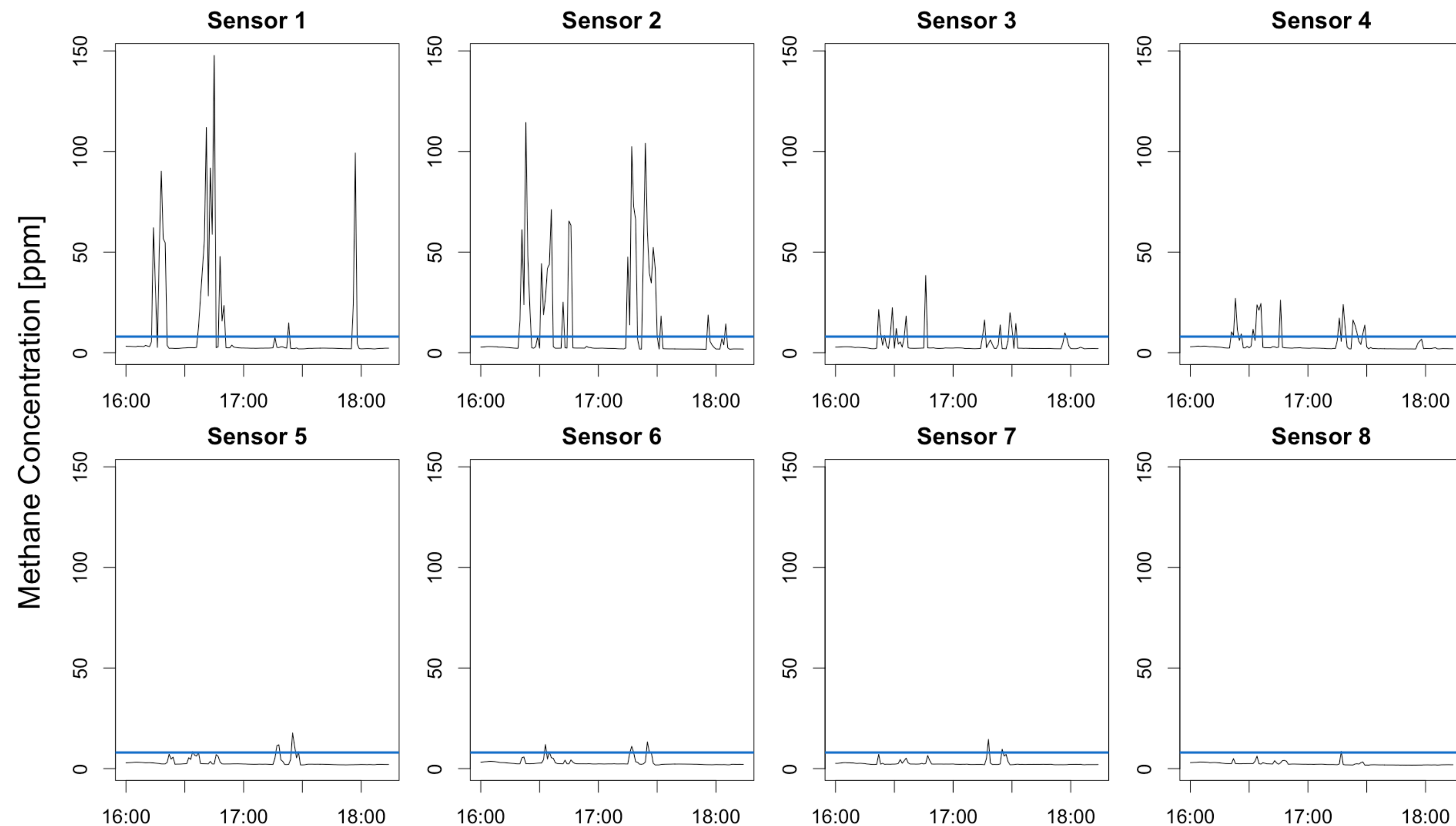
Given a number of continuous monitoring sensors on an oil and gas facility, can we deliver concise alerts when an actionable event occurs?

- Continuous monitoring data from Project Canary
 - Sensors report minute-averaged observations
 - E.g., methane concentration, wind speed, wind direction



The motivation

Alerting on static thresholds can overwhelm operator and does not utilize information from all units simultaneously



Alert Log

	A	B	C
1	time	sensor	concentration
2	2/16/21 16:14	1	62.12096162
3	2/16/21 16:15	1	32.81096162
4	2/16/21 16:17	1	51.36796162
5	2/16/21 16:18	1	90.21896162
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22	2/16/21 16:28	3	9.788987552
23	2/16/21 16:29	3	22.37298755
24	2/16/21 16:31	2	44.24248963
25	2/16/21 16:31	3	12.02098755
26	2/16/21 16:32	2	18.86448963
27	2/16/21 16:32	4	11.6609834
28	2/16/21 16:33	2	27.16248963
29	2/16/21 16:33	6	11.97362448
30	2/16/21 16:34	2	41.88248963
31	2/16/21 16:34	4	23.7939834
32	2/16/21 16:34	5	8.417526971

The plan

Proposed solution: Semi-real time event detection and localization utilizing:

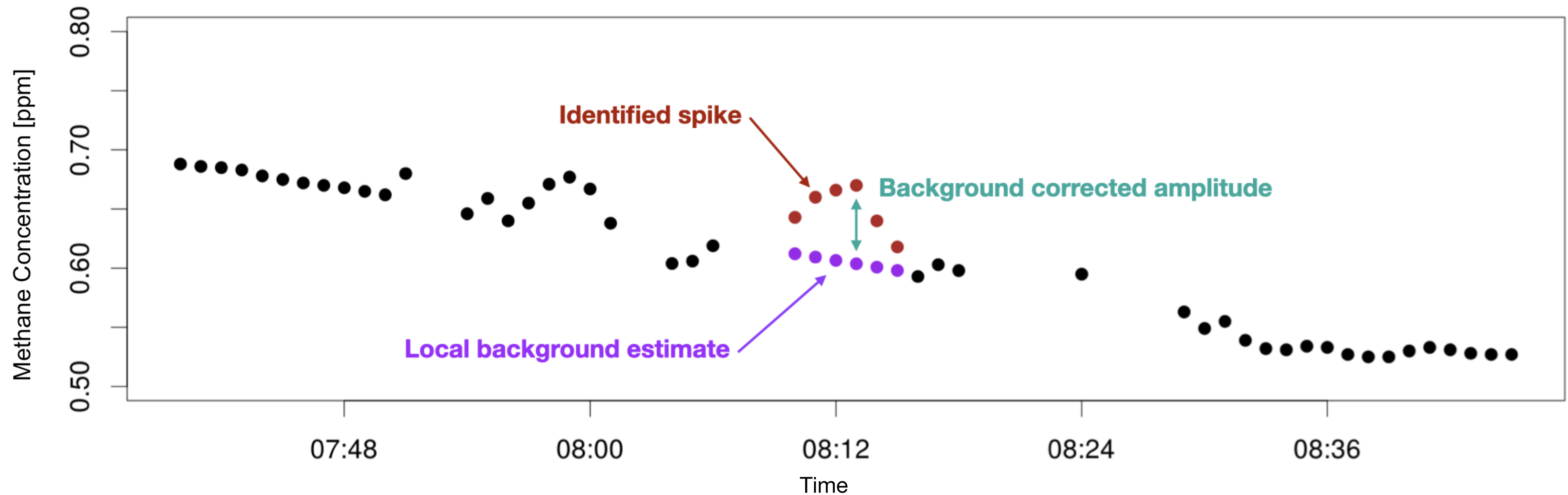
1. Site geometry, including knowledge about all potential sources
2. Information from all available methane and wind sensors

Method:

1. Remove background from sensor observations
2. Simulate concentrations at sensor locations from all potential emission sources
3. Pattern match simulated concentrations and observations via custom metric to identify most likely source for each sensor
4. Use wind data and site geometry to combine information across sensors

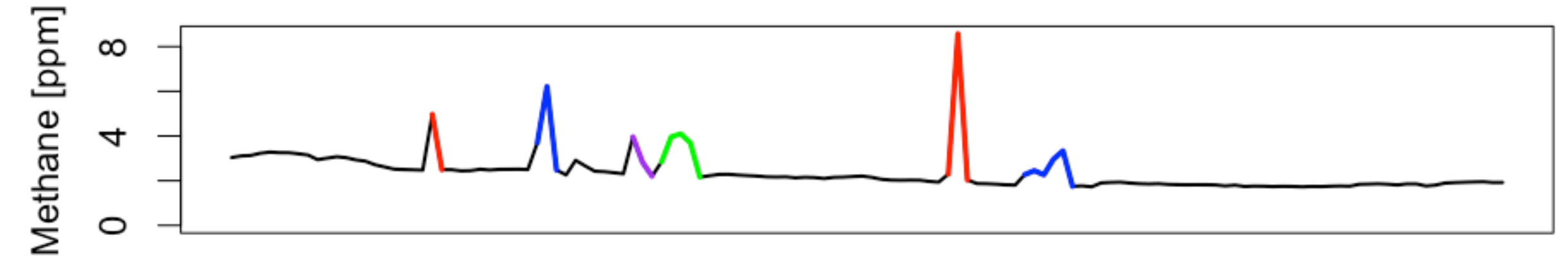
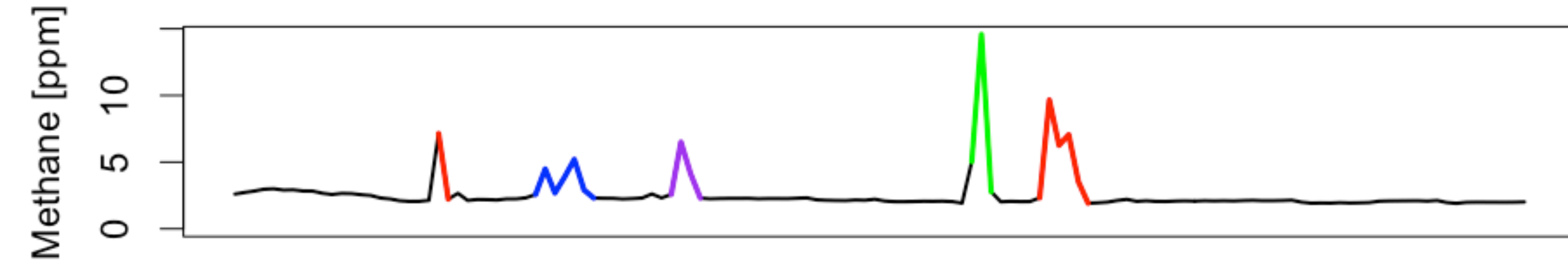
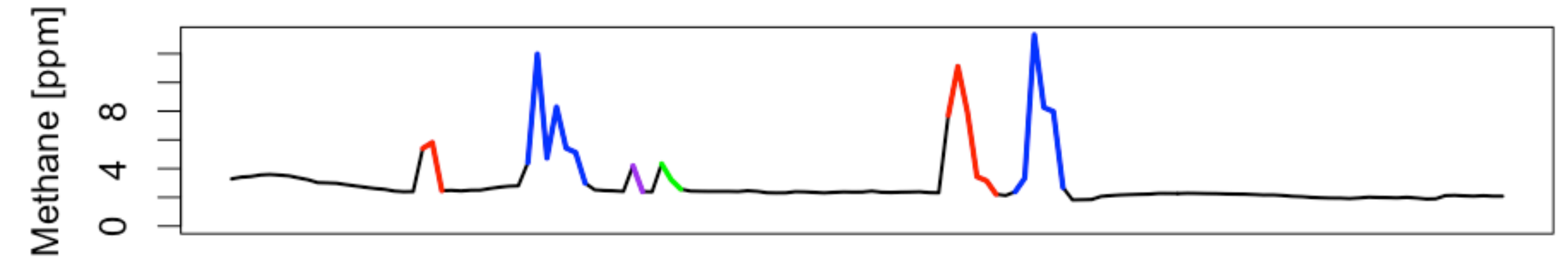
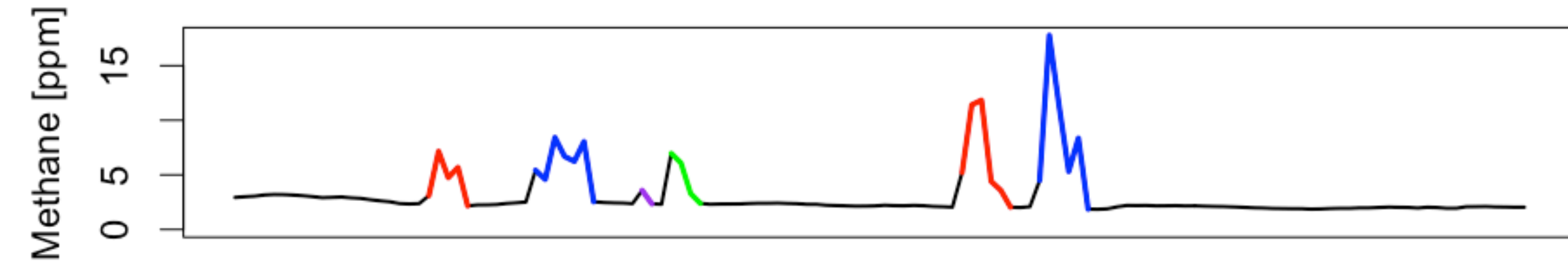
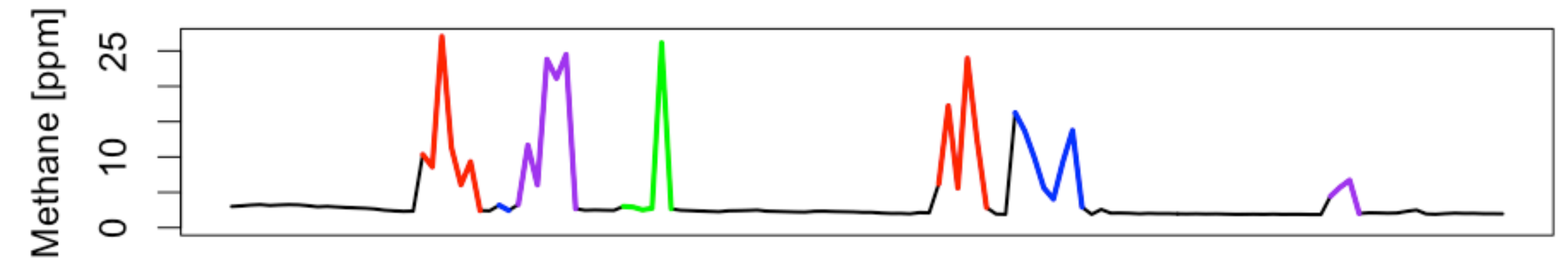
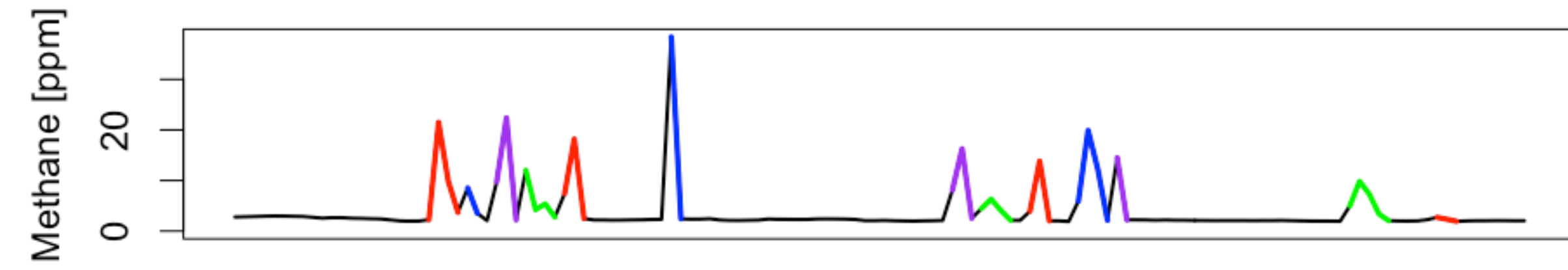
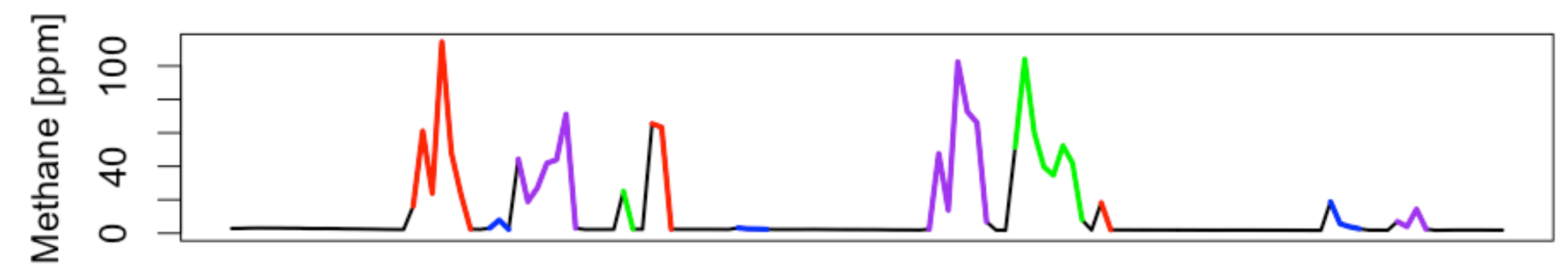
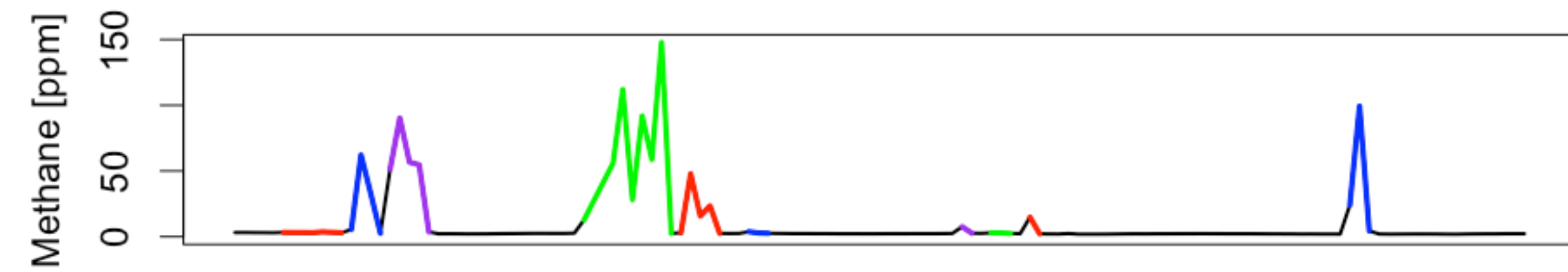
Step 1: Estimate background

- Detect spikes via custom gradient-based method
- Estimate background via non-parametric regression fit to local “non-spike” observations



Step 1: Estimate background

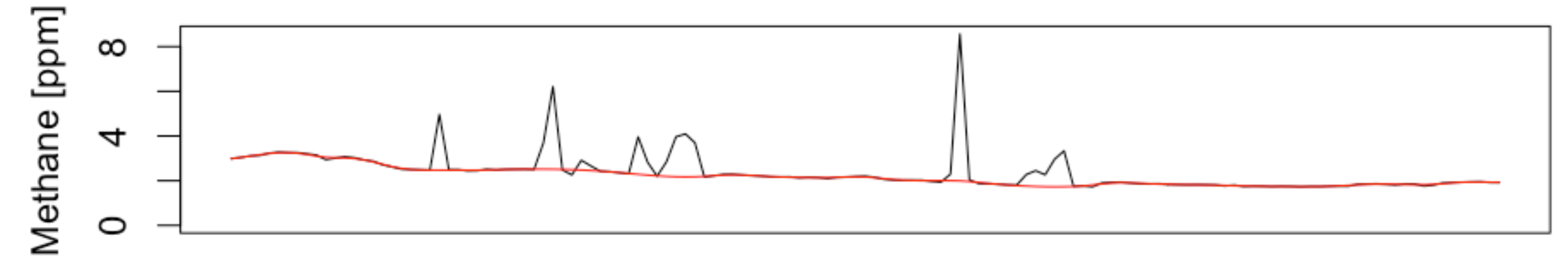
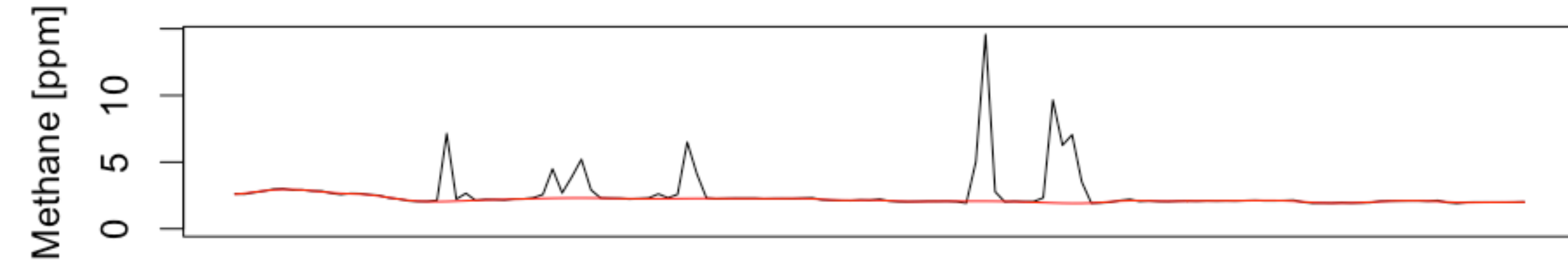
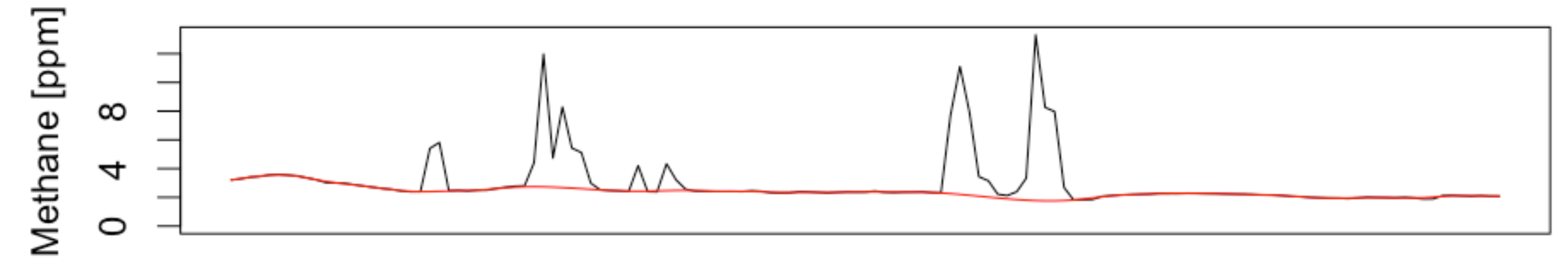
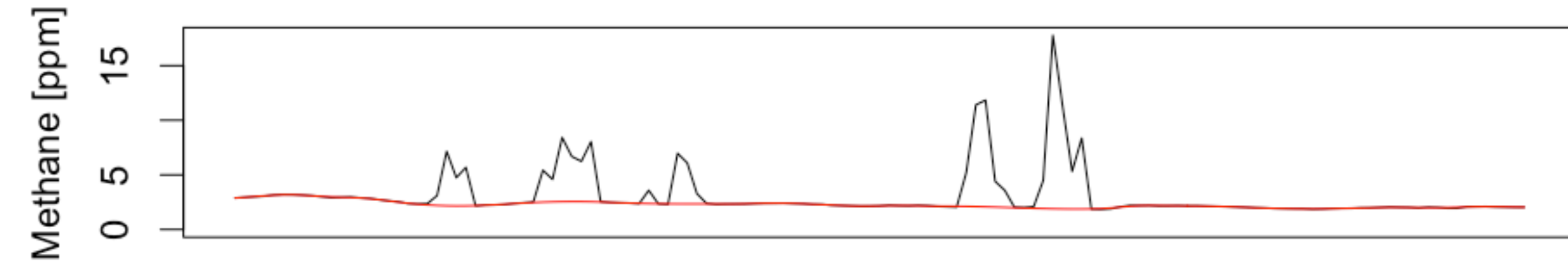
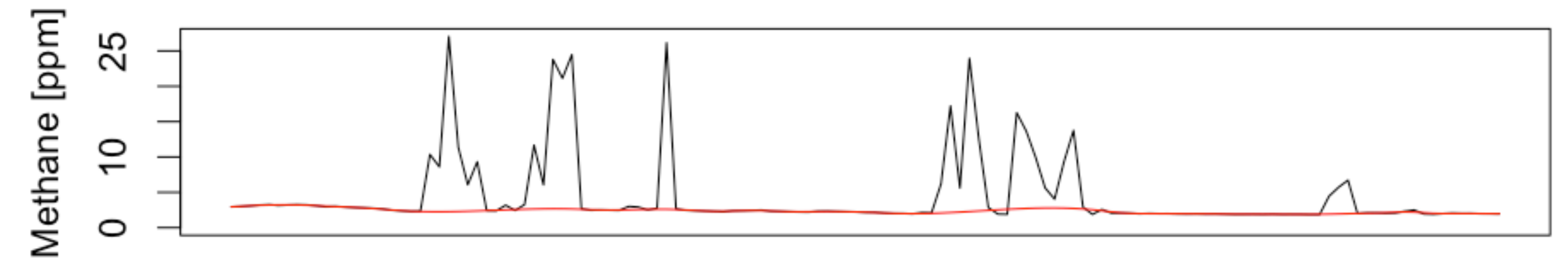
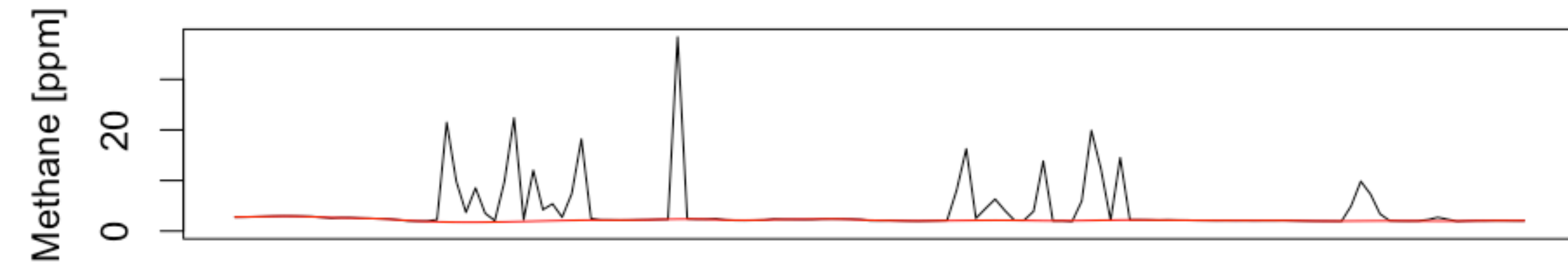
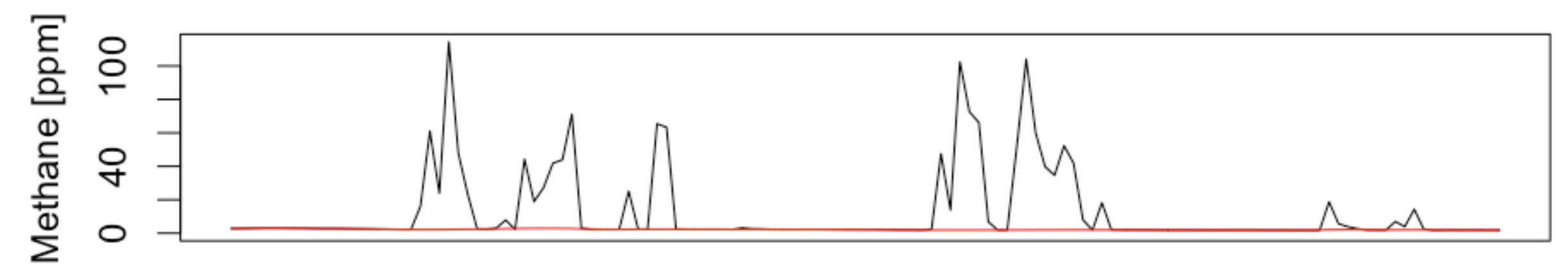
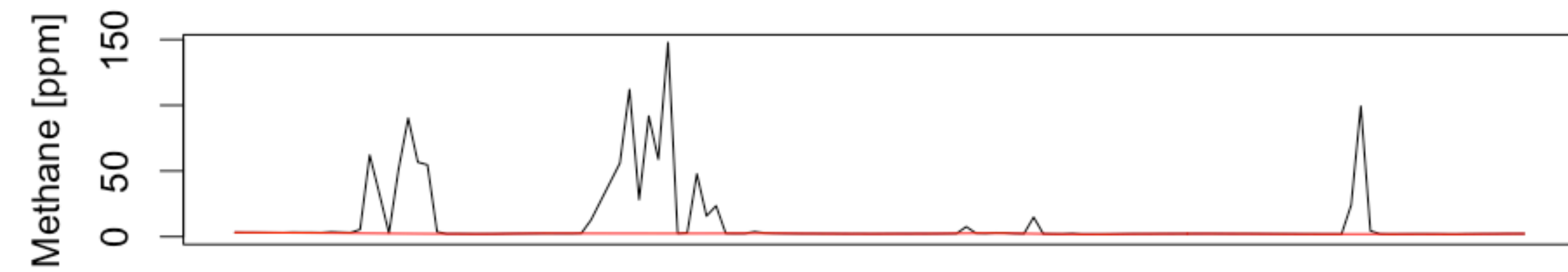
Colors distinguish between different spikes



Time

Time

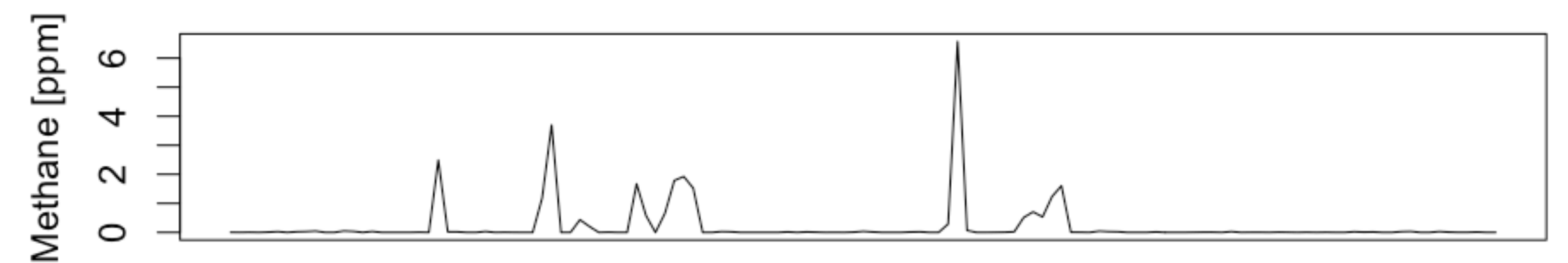
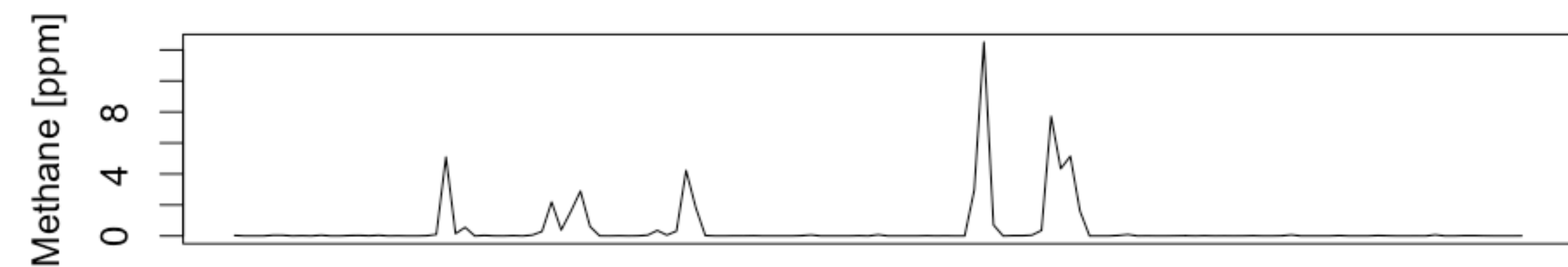
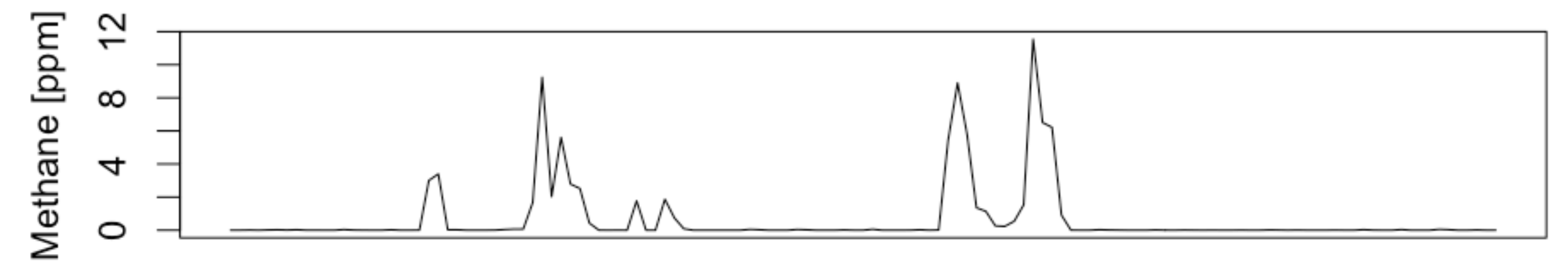
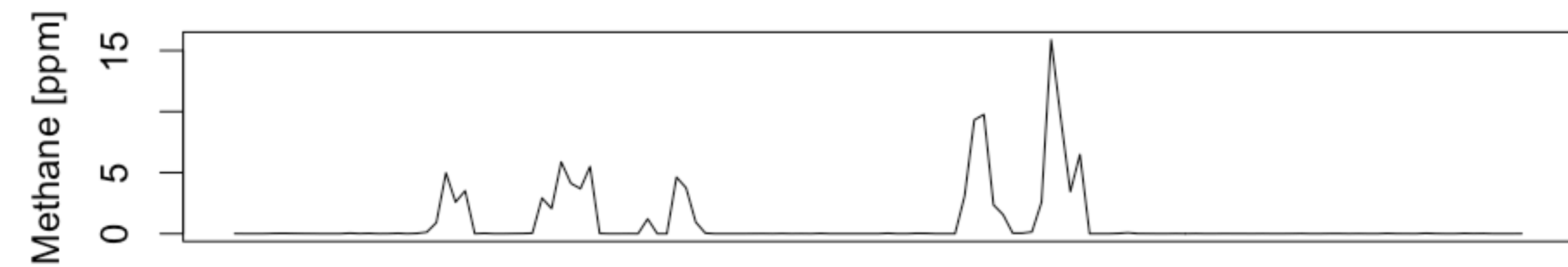
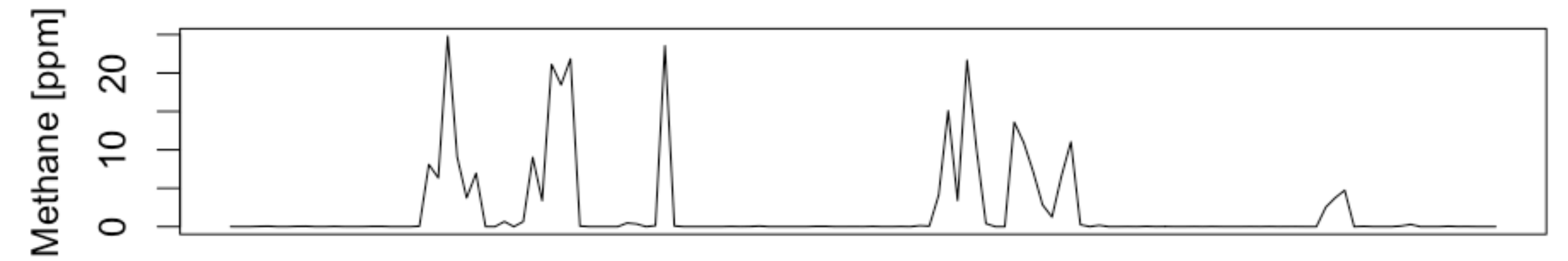
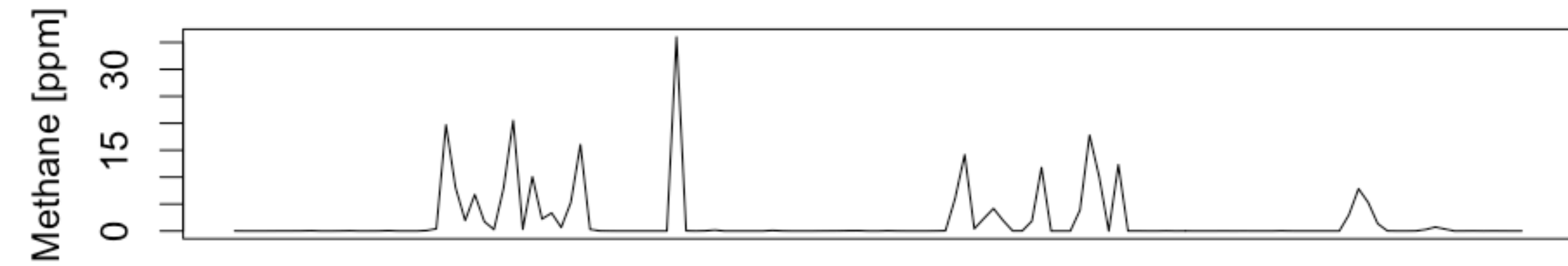
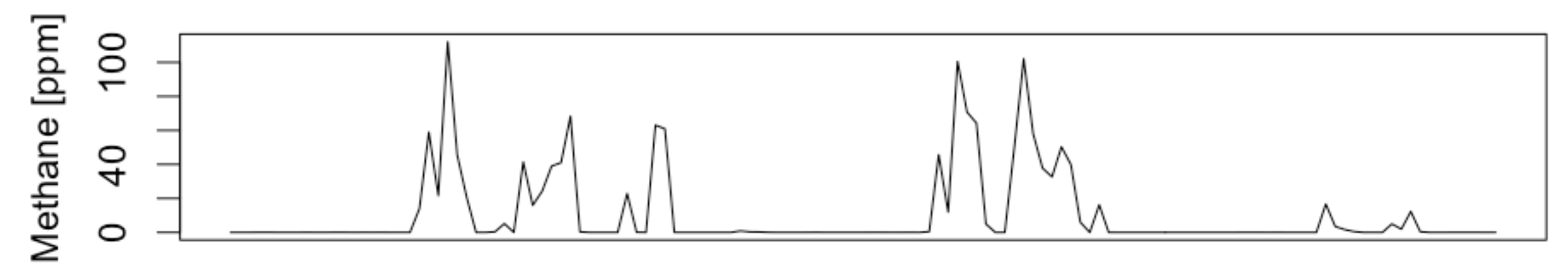
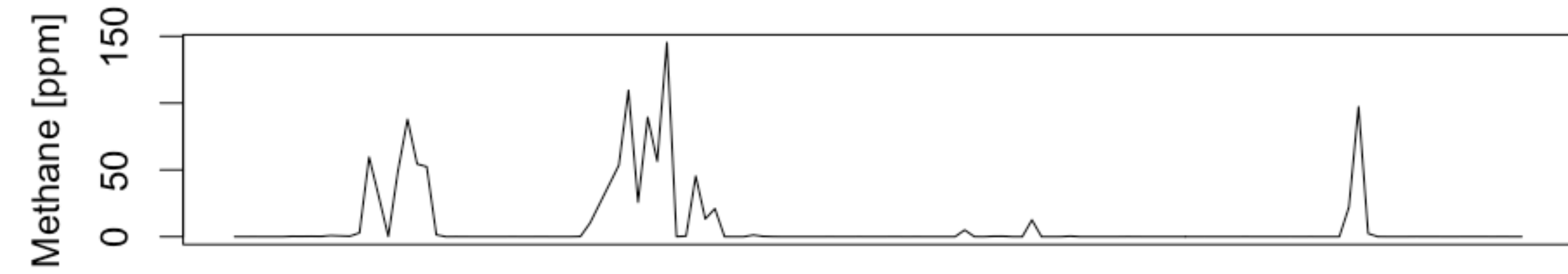
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Time

Time

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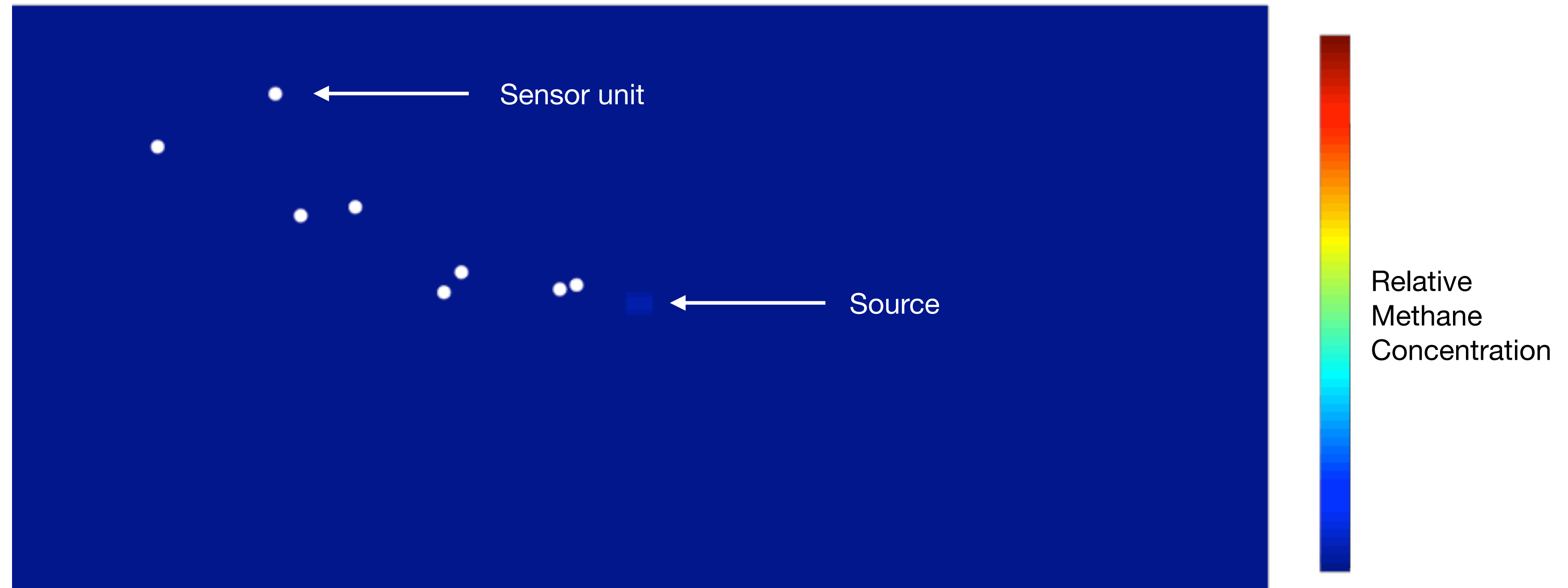
Step 2: Simulate concentrations

- Forward model: Gaussian puff with different horizontal and vertical variances

$$C(x, y, z, t) = \frac{Q_t}{(2\pi)^{\frac{3}{2}} \sigma_y^2 \sigma_z} \exp\left(-\frac{(x - ut)^2 + y^2}{2\sigma_y^2}\right) \left[\exp\left(-\frac{(z - H)^2}{2\sigma_z^2}\right) + \exp\left(-\frac{(z + H)^2}{2\sigma_z^2}\right) \right]$$

- Where:
 - $C(x, y, z, t)$ is the predicted concentration at location (x, y, z) and time t
 - Q_t is the amount of methane released at time t
 - u is the wind speed at time t
 - H is the height of the source

Step 2: Simulate concentrations



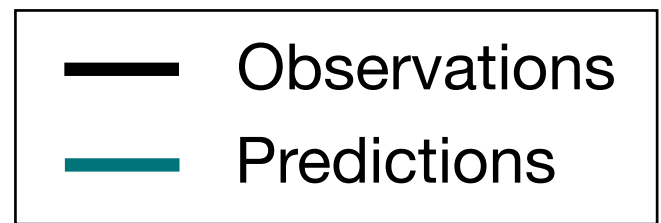
Step 2: Simulate concentrations

Compute simulation predictions from all possible sources

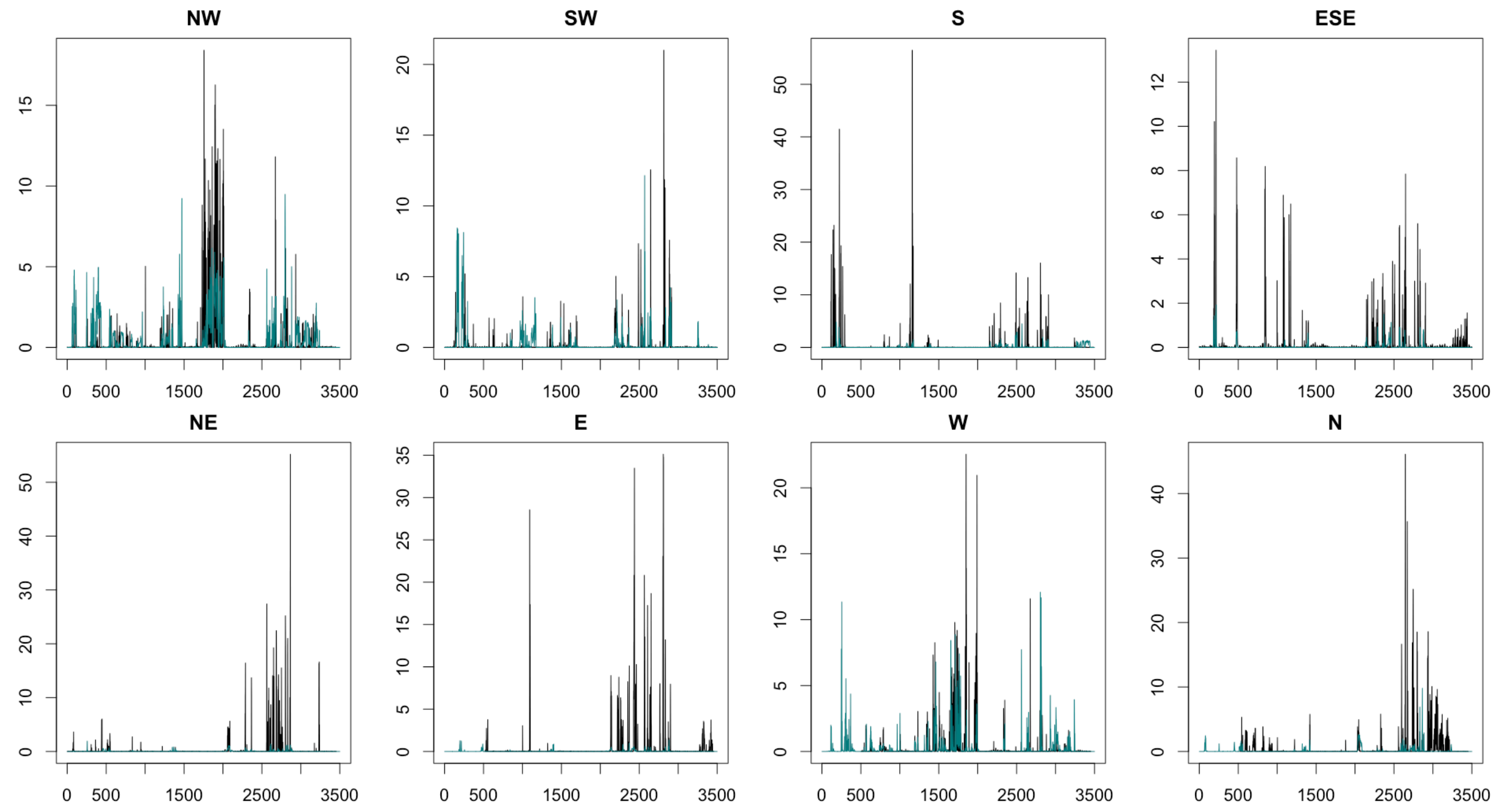


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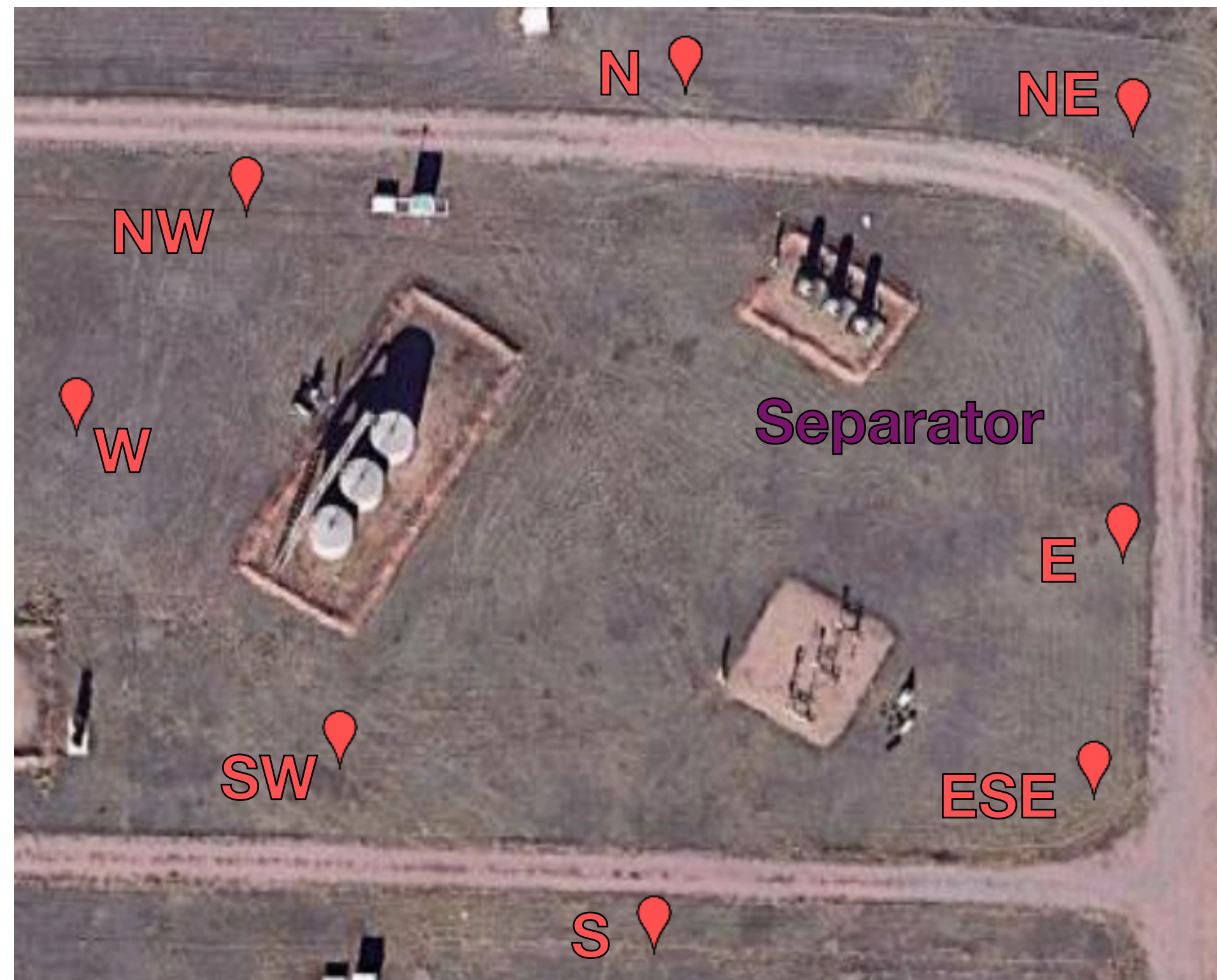
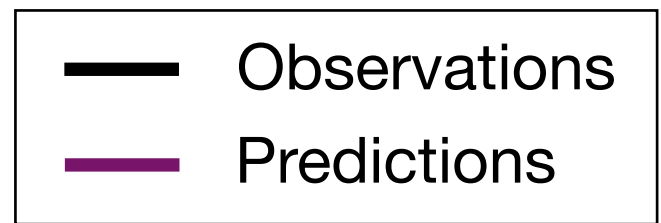
Source: Tanks



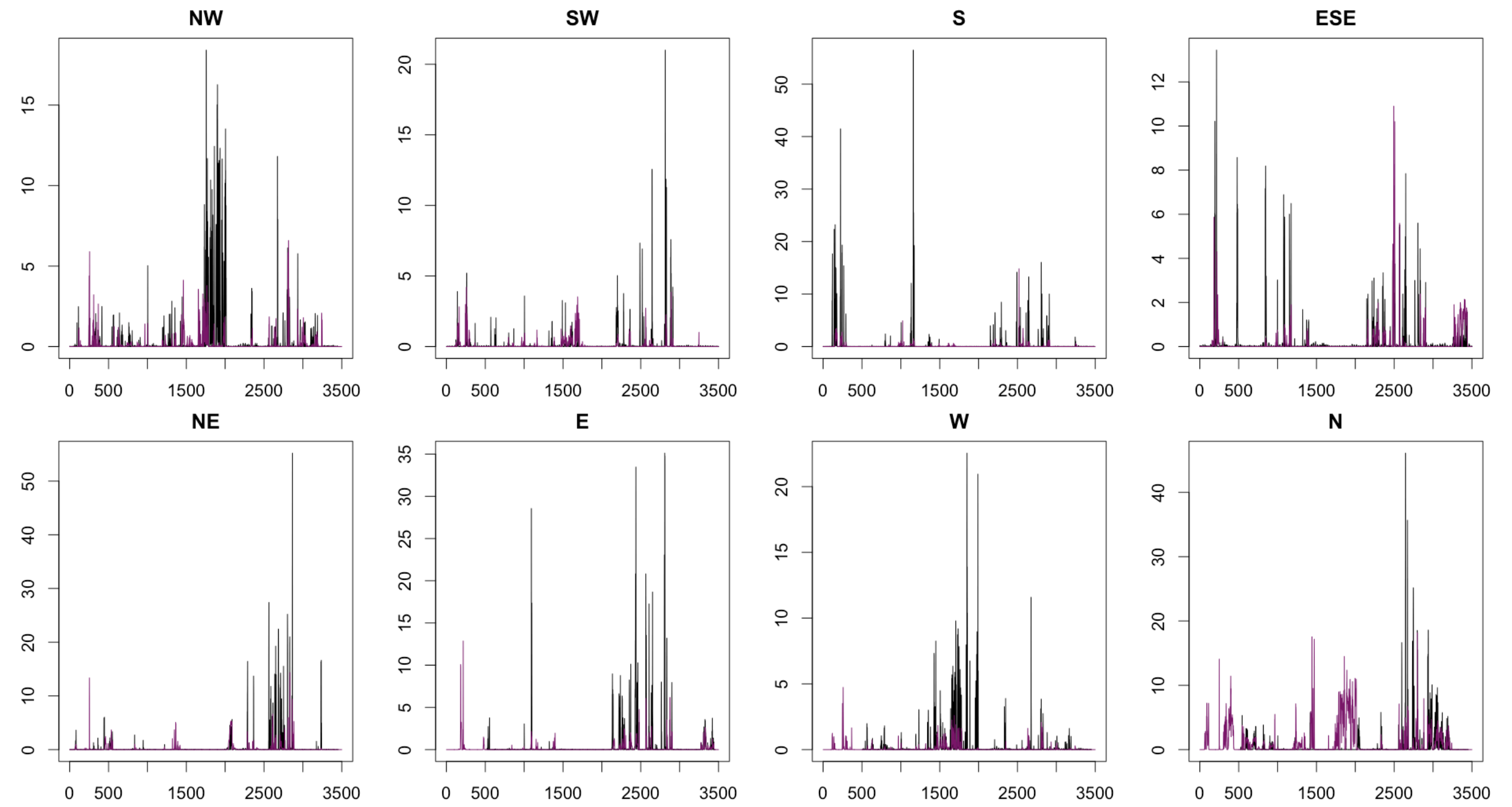
Time

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Compute simulation predictions from all possible sources



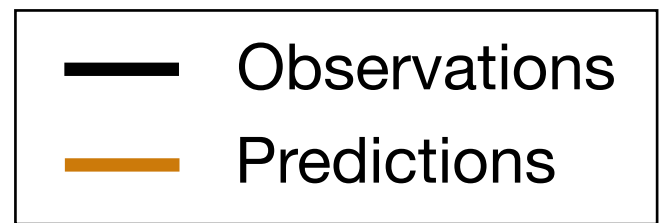
Source: Separator



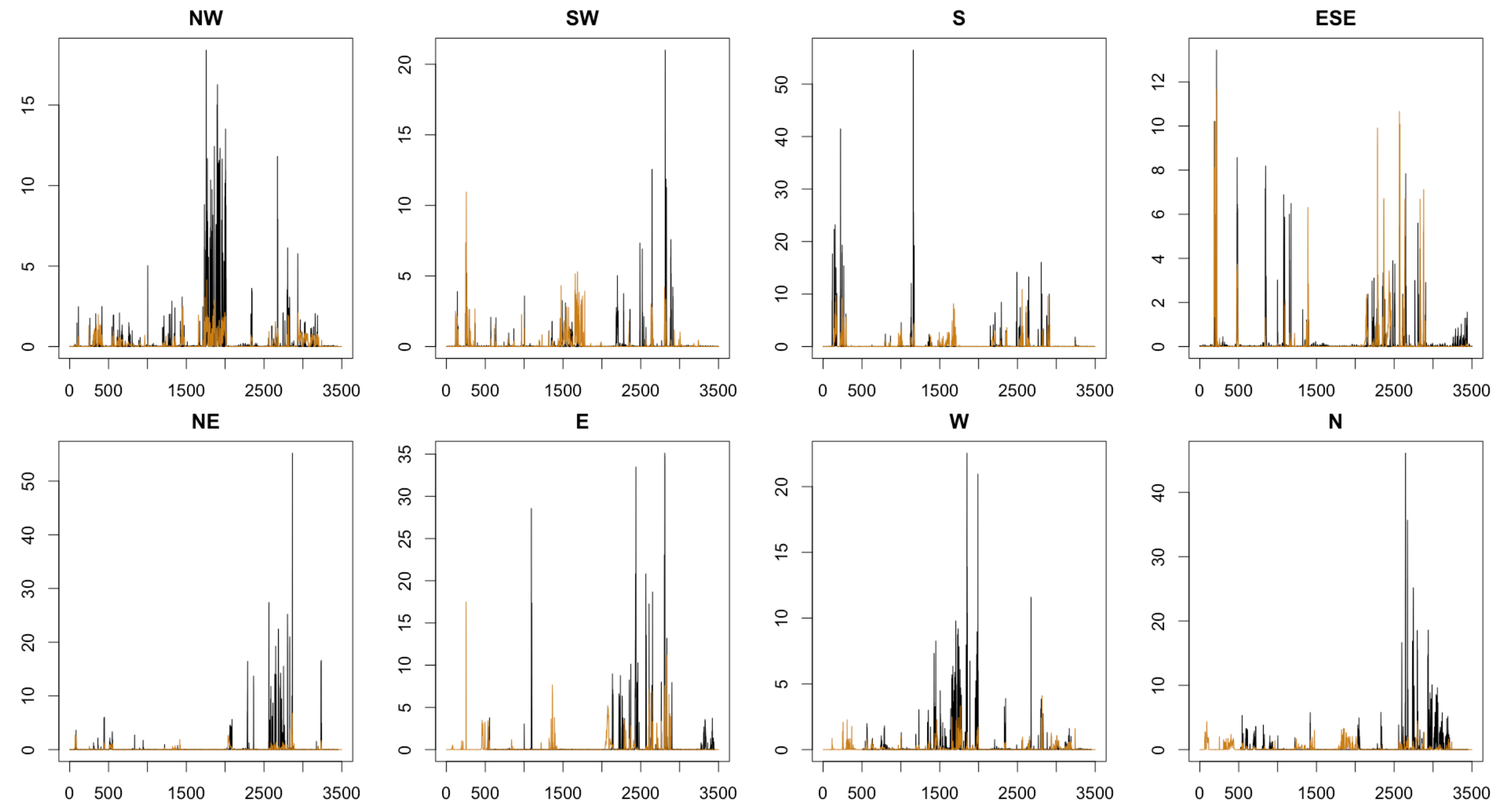
Time

Step 2: Simulate concentrations

Compute simulation predictions from all possible sources



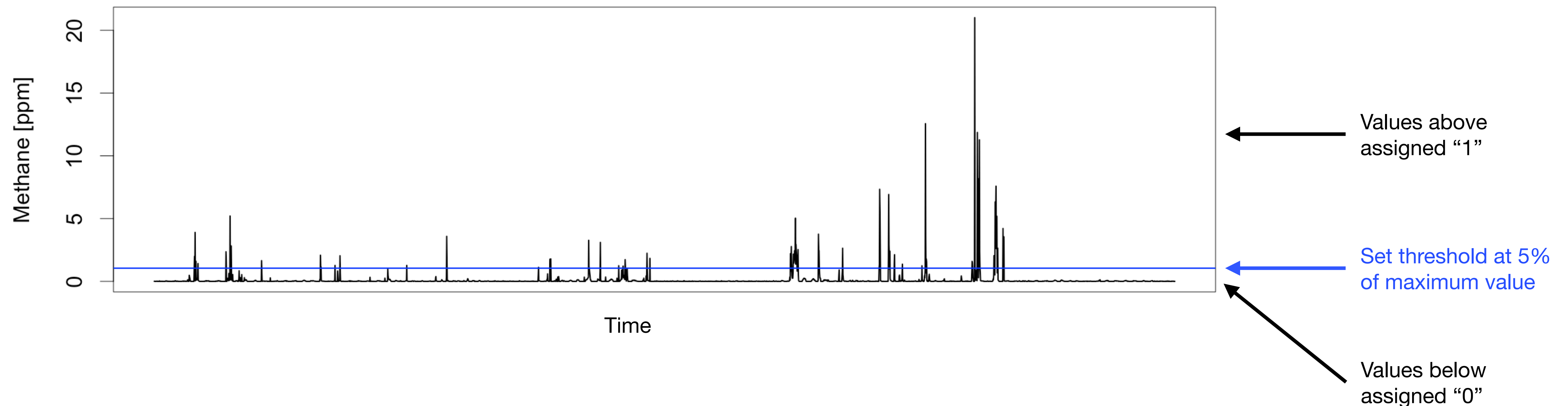
Source: Wellhead



Time

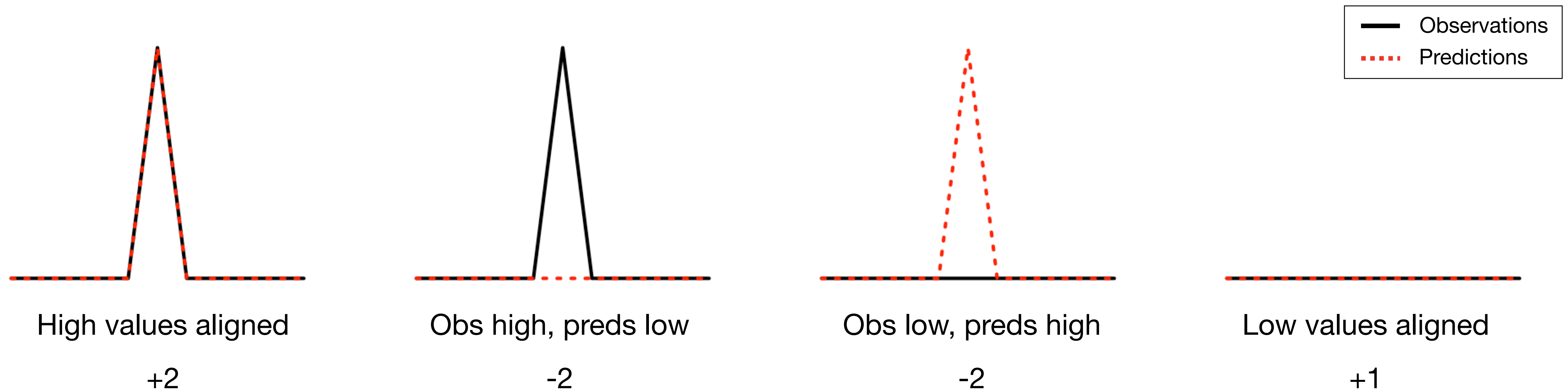
Step 3: Pattern match

- True emission rate unknown in practice: focus on spike alignment, not on amplitude alignment
- Convert observations and predictions into a binary representation: high or low



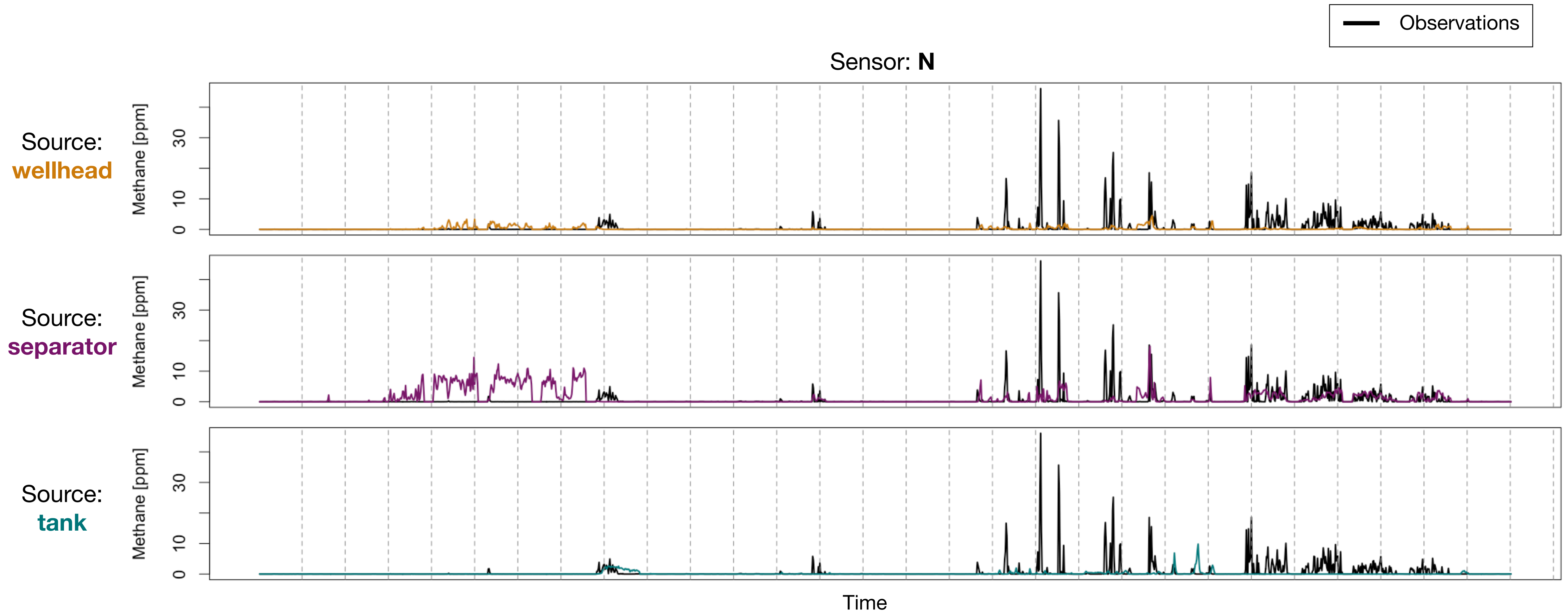
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- True emission rate unknown in practice: focus on spike alignment, not on amplitude alignment
- Convert observations and predictions into a binary representation: high or low
- For each simulation, compute “points” in the following manner



Step 3: Pattern match

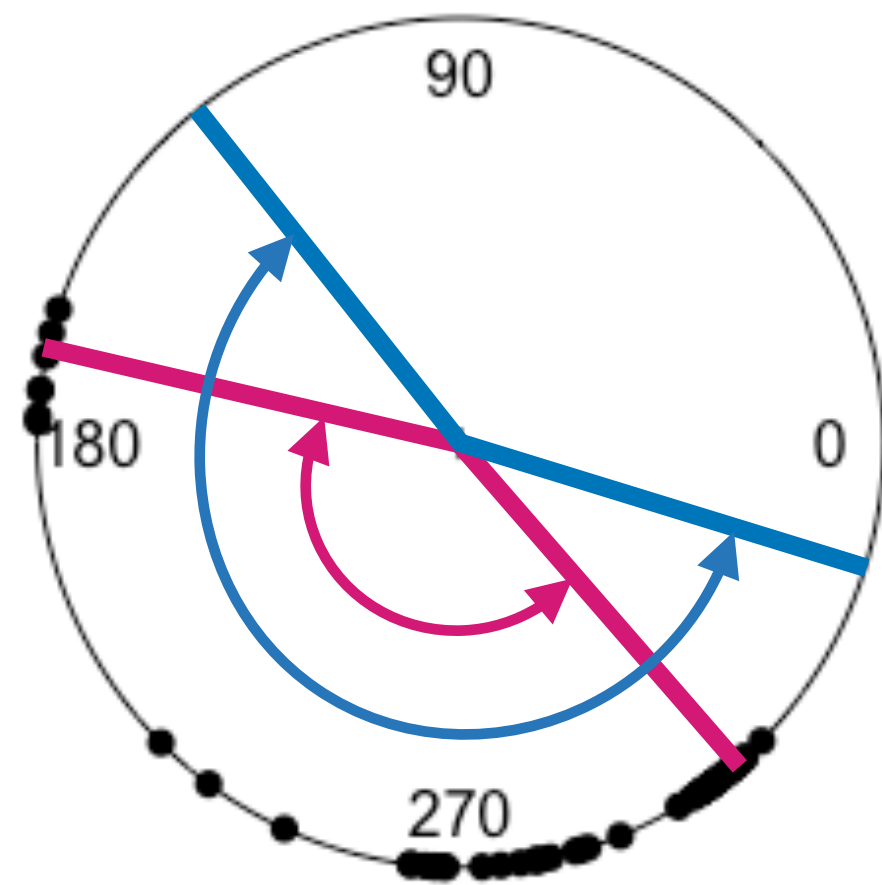
- Perform pattern matching algorithm on small time chunks to account for time varying sources



Step 4: Combine sensors

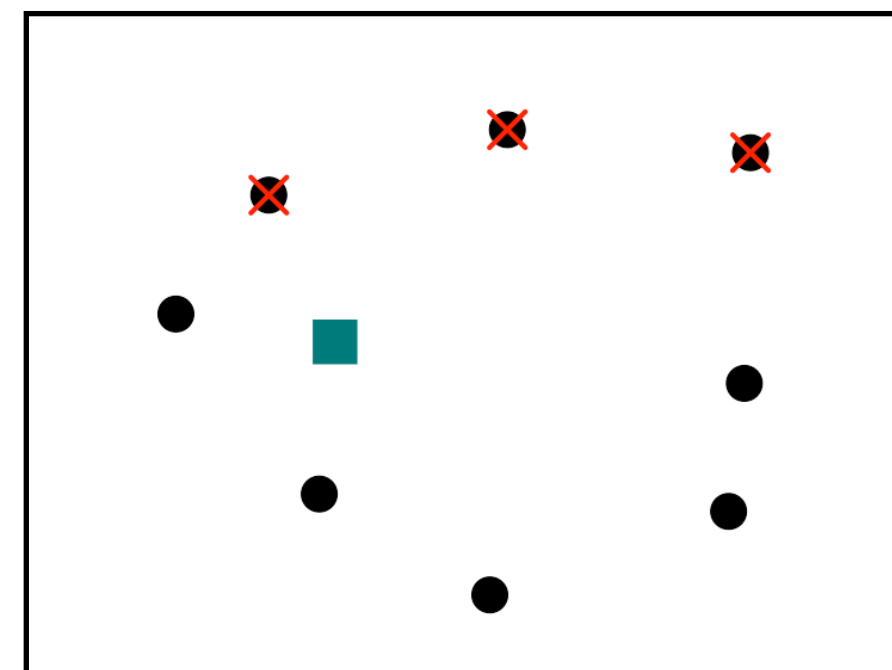
The plan: For each time chunk and for each source, omit data from upwind sensors and average metric across downwind sensors

Example: Consider a single 60 minute time chunk

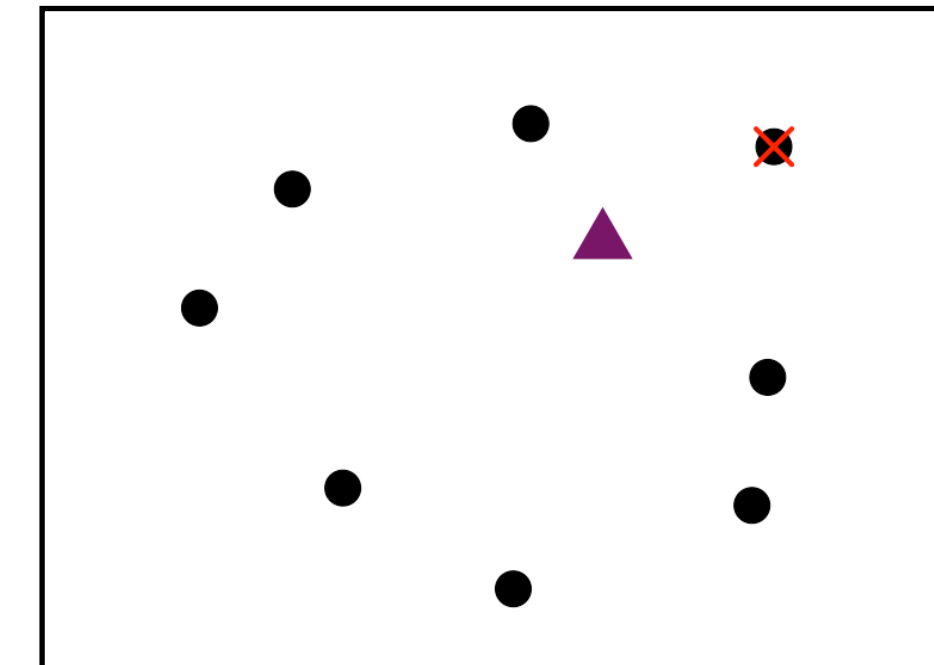


- Wind direction of each observation
- 10th and 90th percentiles
- Extended downwind range

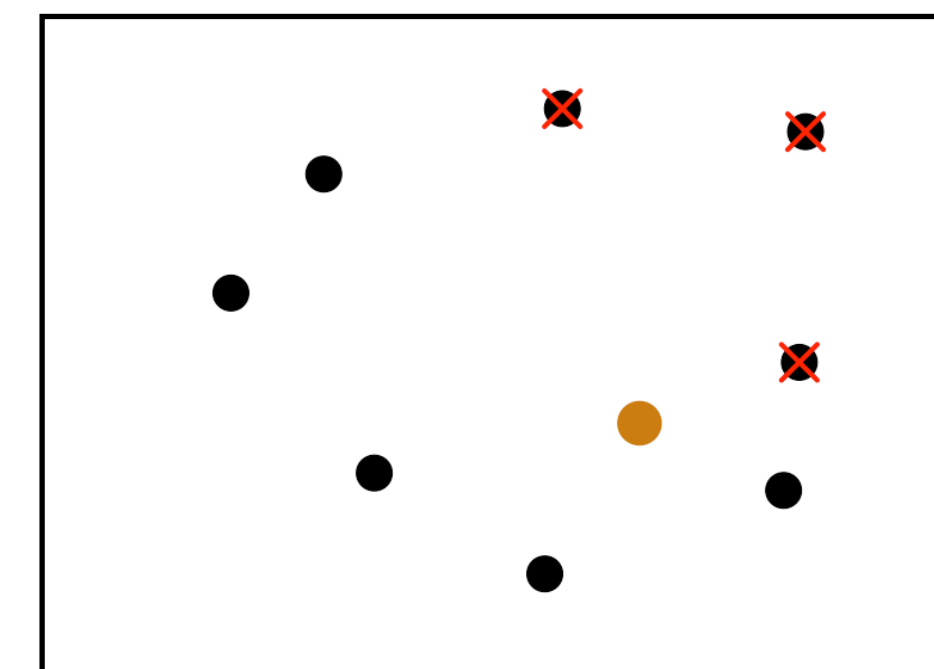
Source: tanks



Source: separator



Source: wellhead



Results

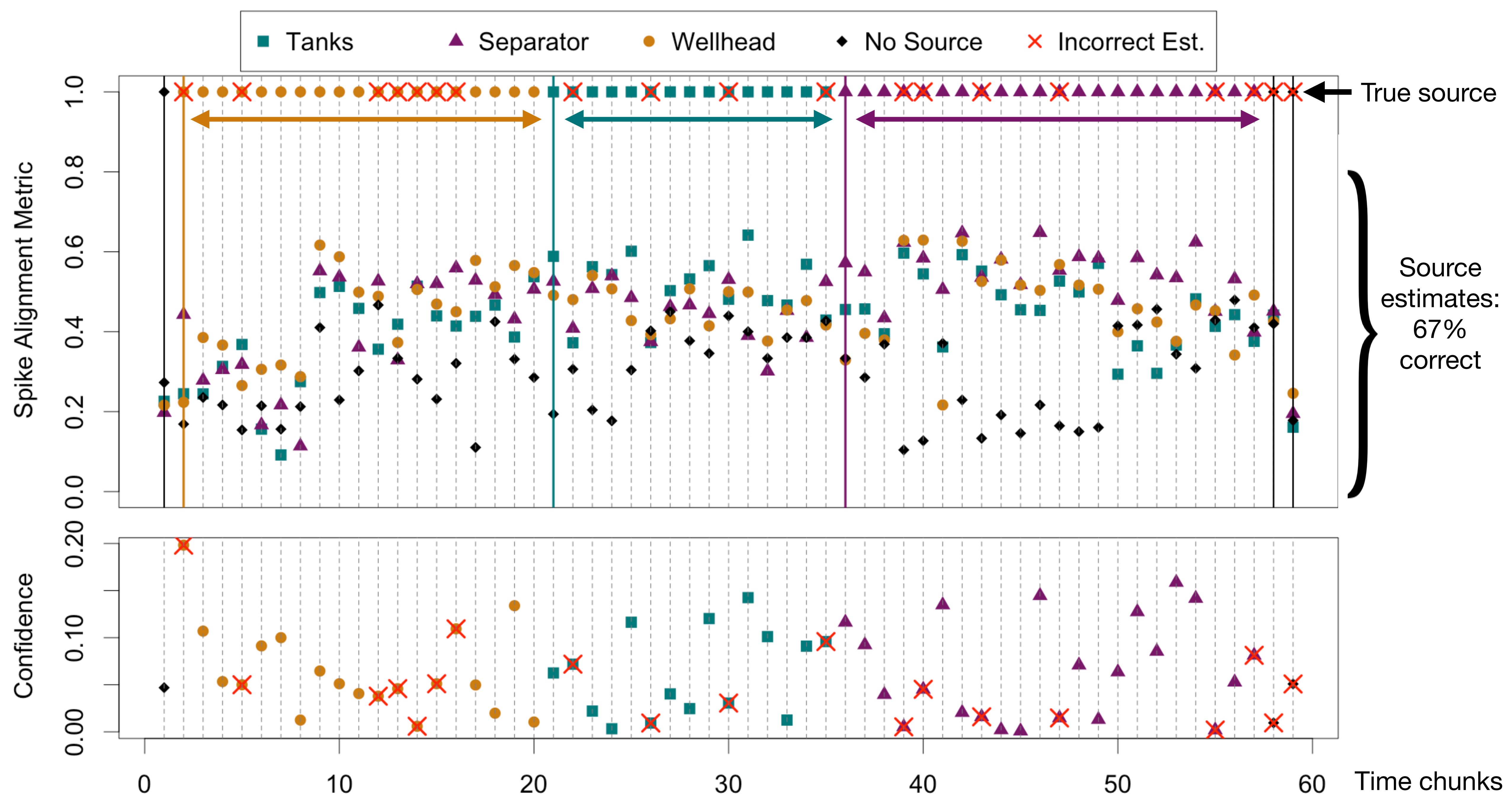


Experimental setup

- 3 potential sources: tanks, separator, wellhead
- 8 sensors
- 58 hours of data (observations taken every minute)

Emission profile

- Controlled experiment
- Only one source emits at a time
- True source and emission rate changes over time



Results



What about a more realistic sensor arrangement?

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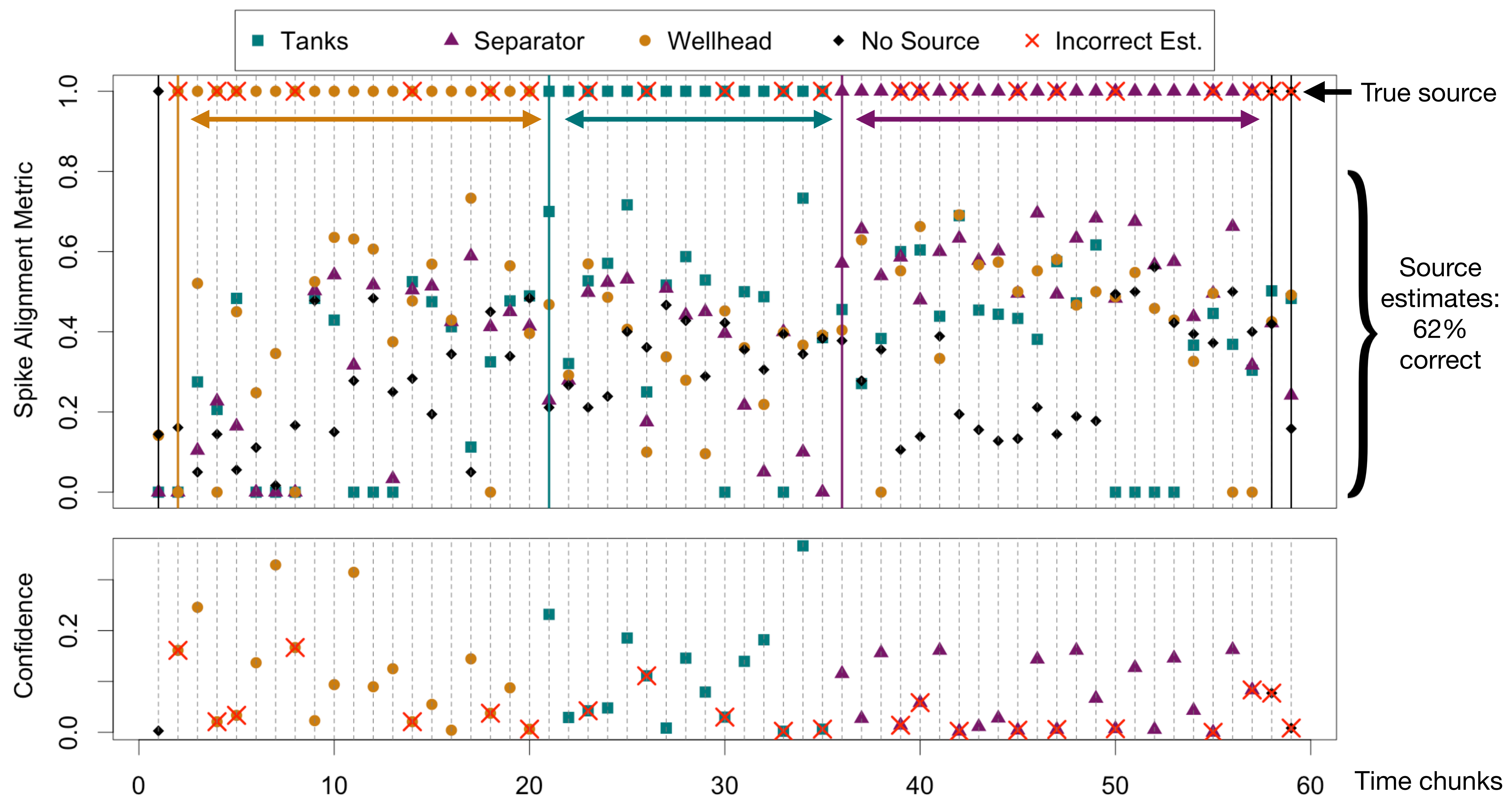
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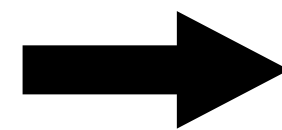


Summary

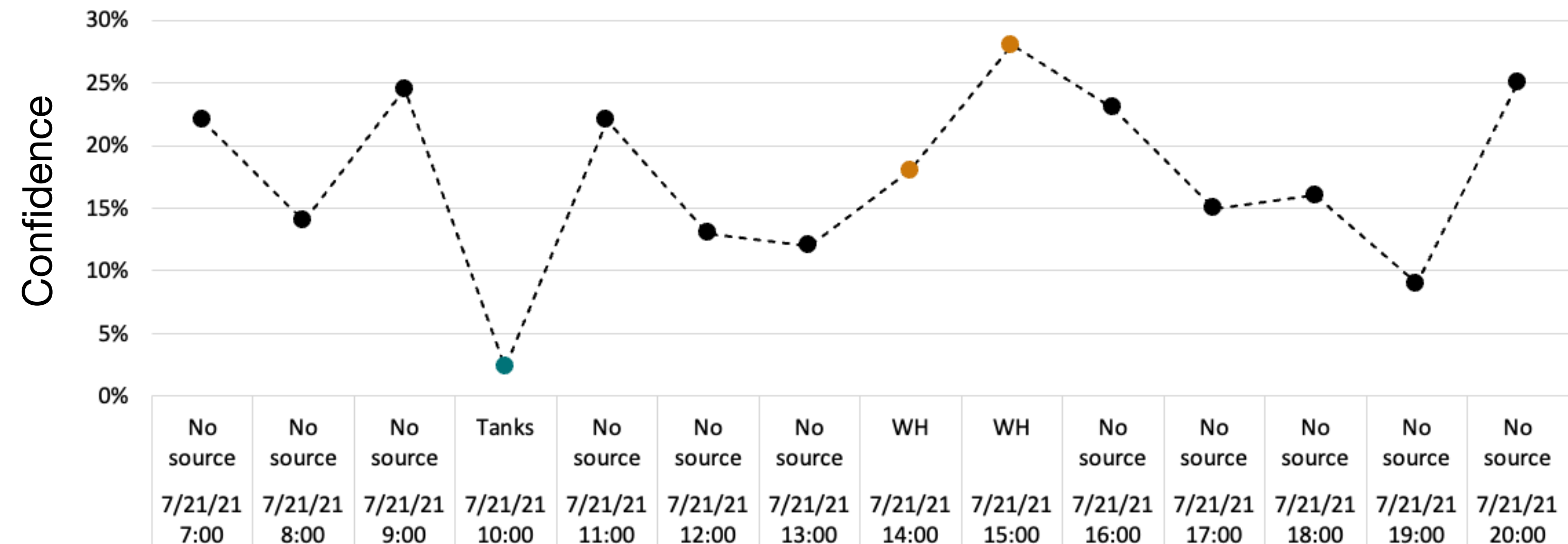
1. Not doing a full inversion, but using a forward model for each potential source to inform localization
2. Using wind direction when combining sensors maximizes contribution of meaningful signal
3. Framework performs well in practical scenario
4. Framework does not depend on true emission rate

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Potential Dashboard





Thank you! Questions?

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